

# NEUMANN BOUNDARY VALUE PROBLEM FOR GERNERA CURVATURE FLOW WITH FORCING TERM

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**ABSTRACT.** In this paper, we prove long time existence and convergence results for a class of general curvature flows with Neumann boundary condition. This is the first result for the Neumann boundary problem of non Monge-Ampere type curvature equations. Our method also works for the corresponding elliptic setting.

## 1. INTRODUCTION

This paper, we consider the deformation of convex graphs over bounded, convex domains  $\Omega \subset \mathbb{R}^n, n \geq 2$ , to convex graphs with prescribed general curvature and Neumann boundary condition. More precisely, let  $\Sigma(t) = \{X := (x, u(x, t)) | (x, t) \in \Omega \times [0, T]\}$ , we study the long time existence and convergence of the following flow problem

$$(1.1) \quad \begin{cases} \dot{u} = w(f(\kappa[\Sigma(t)]) - \Phi(x, u)) & \text{in } \Omega \times [0, T] \\ u_\nu = \varphi(x, u) & \text{on } \partial\Omega \times [0, T] \\ u|_{t=0} = u_0 & \text{in } \Omega, \end{cases}$$

where  $\Phi, \varphi : \bar{\Omega} \times \mathbb{R} \rightarrow \mathbb{R}$  are smooth functions,  $\nu$  denotes the outer unit normal to  $\partial\Omega$ , and  $u_0 : \bar{\Omega} \rightarrow \mathbb{R}$ , is the initial value. The flow equation in (1.1) is equivalent to say  $X$  satisfies

$$\dot{X} = (f(\kappa[\Sigma(t)]) - \Phi)\mathbf{n},$$

where  $\mathbf{n}$  is the upward unit normal of  $\Sigma(t)$ .

We are going to focus on the locally convex hypersurfaces. Accordingly, the function  $f$  is assumed to be defined in the convex cone  $\Gamma_n^+ \equiv \{\lambda \in \mathbb{R}^n : \text{each component } \lambda_i > 0\}$  in  $\mathbb{R}^n$  and satisfying the fundamental structure conditions:

$$(1.2) \quad f_i(\lambda) \equiv \frac{\partial f(\lambda)}{\partial \lambda_i} > 0 \text{ in } \Gamma_n^+, 1 \leq i \leq n,$$

and

$$(1.3) \quad f \text{ is a concave function.}$$

In addition,  $f$  will be assumed to satisfy some more technical assumptions. These include

$$(1.4) \quad f > 0 \text{ in } \Gamma_n^+, f = 0 \text{ on } \partial\Gamma_n^+,$$

$$(1.5) \quad f(1, \dots, 1) = 1,$$

and

$$(1.6) \quad f \text{ is homogeneous of degree one.}$$

Moreover, for any  $C > 0$  and every compact set  $E \subset \Gamma_n^+$ , there is  $R = R(E, C) > 0$  such that

$$(1.7) \quad f(\lambda_1, \dots, \lambda_{n-1}, \lambda_n + R) \geq C, \forall \lambda \in E.$$

An example of functions satisfies all assumptions above is given by  $f = \frac{1}{2} \left[ H_n^{\frac{1}{n}} + (H_n/H_l)^{\frac{1}{n-l}} \right]$ , where  $H_l$  is the normalized  $l$ -th elementary symmetric polynomial. However, we point out that the pure curvature quotient  $(H_n/H_l)^{\frac{1}{n-l}}$  does not satisfy (1.7).

Since for a graph of  $u$ , the induced metric and its inverse matrix are given by

$$(1.8) \quad g_{ij} = \delta_{ij} + u_i u_j \text{ and } g^{ij} = \delta_{ij} - \frac{u_i u_j}{w^2},$$

where  $w = \sqrt{1 + |Du|^2}$ . Following [2], the principle curvature of graph  $u$  are eigenvalues of the symmetric matrix  $A[u] = [a_{ij}]$ :

$$(1.9) \quad a_{ij} = \frac{\gamma^{ik} u_{kl} \gamma^{lj}}{w}, \text{ where } \gamma^{ik} = \delta_{ik} - \frac{u_i u_k}{w(1+w)}.$$

The inverse of  $\gamma^{ij}$  is denoted by  $\gamma_{ij}$ , and

$$(1.10) \quad \gamma_{ij} = \delta_{ij} + \frac{u_i u_j}{1 + w}.$$

Geometrically  $[\gamma_{ij}]$  is the square root of the metric, i.e.  $\gamma_{ik} \gamma_{kj} = g_{ij}$ . Now, for any positive definite symmetric matrix  $A$ , we define the function  $F$  by

$$F(A) = f(\lambda(A)),$$

where  $\lambda(A)$  denotes the eigenvalues of  $A$ . We will use the notation

$$F^{ij}(A) = \frac{\partial F}{\partial a_{ij}}, \quad F^{ij,kl} = \frac{\partial^2 F}{\partial a_{ij} \partial a_{kl}}(A).$$

The matrix  $[F^{ij}(A)]$  is symmetric and has eigenvalues  $f_1, \dots, f_n$ , and by (1.2),  $[F^{ij}(A)]$  is positive definite. Moreover, by (1.3),  $F$  is a concave function of  $A$ , that is

$$F^{ij,kl}(A) \xi_{ij} \xi_{kl} \leq 0,$$

for any  $n \times n$  matrix  $[\xi_{ij}]$ .

We rewrite equation (1.1) as following

$$(1.11) \quad \begin{cases} \dot{u} = w \left( F \left( \frac{\gamma^{ik} u_{kl} \gamma^{lj}}{w} \right) - \Phi(x, u) \right) & \text{in } \Omega \times [0, T) \\ u_\nu = \varphi(x, u) & \text{on } \partial\Omega \times [0, T) \\ u|_{t=0} = u_0 & \text{in } \Omega, \end{cases}$$

We will prove

**Theorem 1.1.** *Let  $\Omega$  be a smooth bounded, strictly convex domain in  $\mathbb{R}^n$ . Let  $\Phi, \varphi : \bar{\Omega} \times \mathbb{R} \rightarrow \mathbb{R}$ , be smooth functions satisfy*

$$(1.12) \quad \Phi > 0 \text{ and } \Phi_z \geq 0,$$

$$(1.13) \quad \varphi_z \leq c_\varphi < 0.$$

*Let  $u_0$  be a smooth, convex function that satisfies the compatibility condition on  $\partial\Omega$ :*

$$(1.14) \quad \nu^i u_i - \varphi(x, u)|_{t=0} = 0.$$

*Moreover, we assume*

$$(1.15) \quad f(\kappa[\Sigma_0]) - \Phi(x, u_0) \geq 0,$$

*where  $\Sigma_0 = \{(x, u_0(x)) | x \in \Omega\}$ . Then there exists a solution  $u \in C^\infty(\bar{\Omega} \times (0, t)) \cap C^{\alpha+2, 1+\alpha/2}(\bar{\Omega} \times [0, t))$  of equation (1.11) for all  $t > 0$ . As  $t \rightarrow \infty$ , the function  $u(x, t)$  smoothly converges to a smooth limit function  $u^\infty$ , such that  $u^\infty$  satisfies the Neumann boundary value problem*

$$(1.16) \quad \begin{cases} F \left( \frac{\gamma^{ik} u_{kl}^\infty \gamma^{lj}}{w} \right) = \Phi(x, u^\infty) & \text{in } \Omega \\ u_\nu^\infty = \varphi(x, u^\infty) & \text{on } \partial\Omega, \end{cases}$$

*where  $\nu$  is the outer unit normal of  $\partial\Omega$ .*

**Remark 1.2.** The short time existence for equation (1.11) comes from Theorem 5.3 in [6] and the implicit function theorem.

By applying short time existence theorem, we know that the flow exists for  $t \in [0, T^*)$ , for some  $T^* > 0$  very small. In the following sections, we fix  $T < T^*$ , and establish the uniform  $C^2$  bounds for the solution  $u$  of (1.11) in  $(0, T]$ . Since our estimates are independent of  $T$ , repeating this process we obtain the longtime existence of equation (1.11).

Neumann boundary problem has attracted lots of attentions through these years. In particular, the existence for equations of Monge-Ampere type was studied in [7] in the 80s'; later Jiang, Trudinger, and Xiang [5] adapted and developed the methods in [7] to a generalized Monge-Ampere type equation with Neumann boundary condition. Recently, Ma and Qiu proved the existence of solutions to  $\sigma_k$  Hessian equations with Neumann boundary condition in their beautiful paper [8], in this paper they solved a long lasting conjecture by Trudinger in 1986. The Neumann boundary problems for parabolic equation have been widely studied too. For example, mean curvature flow with Neumann boundary condition have been studied in [1, 3, 10]; Guass curvature flow with Neumann boundary condition have been studied in [9].

Our paper is organized as follows: In Section 2 we prove the uniform estimate for  $\dot{u}$ , which also implies the convexity for  $u(\cdot, t), t \in [0, T]$ . This is used in Section 3 to derive the  $C^0$  and  $C^1$  estimates. Section 4 is the most important section, in which we derive the  $C^2$  estimates for  $u$ . Finally, in Section 5 we combine all results above to prove the convergence of solution of (1.11) as  $t \rightarrow \infty$ .

## 2. SPEED ESTIMATE

**Lemma 2.1.** *As long as a smooth convex solution of (1.11) exists, we have*

$$(2.1) \quad \min\{\min_{t=0} \dot{u}, 0\} \leq \dot{u} \leq \max\{\max_{t=0} \dot{u}, 0\}.$$

*Proof.* If  $(\dot{u})^2$  achieves a positive local maximum at  $(x, t) \in \partial\Omega \times [0, T]$  then at this point we would have

$$(2.2) \quad (\dot{u})_\nu^2 = 2\dot{u}\dot{u}_\nu = 2(\dot{u})^2\varphi_z < 0,$$

which leads to a contradiction. Thus, we assume  $(\dot{u})^2$  achieves maximum at an interior point. Now let's denote

$$\tilde{G}(D^2u, Du, u) = wF\left(\frac{\gamma^{ik}u_{kl}\gamma^{lj}}{w}\right) - w\Phi(x, u)$$

and  $r = (\dot{u})^2$ . Then, a straight forward calculation gives us

$$(2.3) \quad \dot{r} = \tilde{G}^{ij}r_{ij} - 2\tilde{G}^{ij}\dot{u}_i\dot{u}_j + \tilde{G}^s r_s + 2\tilde{G}_u r.$$

Since

$$(2.4) \quad \tilde{G}_u := \frac{\partial \tilde{G}}{\partial u} = -w\Phi_u \leq 0,$$

we have

$$(2.5) \quad \dot{r} - \tilde{G}^{ij} r_{ij} - \tilde{G}^s r_s \leq 0.$$

By the maximum principle we know that a positive local maximum of  $(\dot{u})^2$  can not occur at an interior point of  $\Omega \times (0, T]$ . Therefore, we proved this Lemma.  $\square$

**Lemma 2.2.** *A solution of (1.11) satisfies  $\dot{u} > 0$  for  $t > 0$  if  $0 \not\equiv \dot{u} \geq 0$  for  $t = 0$ .*

*Proof.* Since

$$(2.6) \quad \dot{u} = \tilde{G}(D^2 u, Du, u),$$

differentiating it with respect to  $t$  we get

$$(2.7) \quad \frac{d}{dt} u_t = \tilde{G}^{ij} (u_t)_{ij} + \tilde{G}^s (u_t)_s + \tilde{G}_u u_t.$$

Therefore, for any constant  $\lambda$  we have

$$(2.8) \quad \frac{d}{dt} (u_t e^{\lambda t}) = \tilde{G}^{ij} (u_t e^{\lambda t})_{ij} + \tilde{G}^s (u_t e^{\lambda t})_s + \tilde{G}_u (u_t e^{\lambda t}) + \lambda u_t e^{\lambda t}.$$

We fix  $t_0 > 0$  and a constant  $\lambda$  such that  $\lambda + \tilde{G}_u > 0$  for  $(x, t) \in \bar{\Omega} \times [0, t_0]$ . By the strong maximum principle we see that  $u_t e^{\lambda t}$  has to vanish identically if it vanishes in  $\Omega \times (0, t_0)$ , which leads to a contradiction.

If  $u_t e^{\lambda t} = 0$  for  $(x, t) \in \partial\Omega \times (0, t_0)$ , then we would have

$$(2.9) \quad (u_t e^{\lambda t})_\nu = \varphi_z(u_t e^{\lambda t}) = 0$$

contradicts the Hopf Lemma.  $\square$

**Remark 2.3.** Lemma 2.2 implies that, if we start from a strictly convex surface  $\Sigma_0$  satisfies (1.15), then as long as the flow exists, the flow surfaces  $\Sigma(t)$  are strictly convex and satisfies  $f(\kappa[\Sigma(t)]) - \Phi(x, u) > 0$ .

### 3. $C^0$ AND $C^1$ ESTIMATES

The strict convexity of  $u$  and the fact that  $\varphi(\cdot, z) \rightarrow -\infty$  uniformly as  $z \rightarrow \infty$  implies that  $u$  is uniformly bounded from above. By Lemma 2.2

$$(3.1) \quad u(x, t) = u(x, 0) + \int_0^t \dot{u}(x, \tau) d\tau \geq u(x, 0)$$

we know  $u$  is bounded from below as well. To conclude, we have

**Theorem 3.1** ( $C^0$  estimates). *Under our assumption (1.15) on  $u_0$ , a solution of equation (1.11) satisfies*

$$(3.2) \quad |u| \leq C_0,$$

where  $C_0 = C_0(u_0, \varphi)$ .

**Theorem 3.2** ( $C^1$  estimates). *For a convex solution  $u$  of equation (1.11), the gradient of  $u$  remains bounded during the evolution,*

$$(3.3) \quad |Du| \leq C_1,$$

where  $C_1 = C_1(|u|_{C^0}, \Omega, \varphi)$ .

*Proof.* The proof is the same as Theorem 2.2 in [7], for readers convenience we include it here. By the convexity of  $u$  we have for any  $t \in [0, T]$

$$(3.4) \quad \max_{\Omega} |Du(\cdot, t)| = \max_{\partial\Omega} |Du(\cdot, t)|.$$

Let  $x_0 \in \partial\Omega$  and let  $\tau$  be a direction such that  $\nu \cdot \tau = 0$  at  $x_0$ . Let  $B = B_R(z)$  be an interior ball at  $x_0$ ,  $L$  be the line through  $x_0$  in the direction of  $-\nu$ , and  $L$  intersects  $\partial B$  at  $y_0$ . Then  $z = \frac{1}{2}(x_0 + y_0)$ , we also let  $y$  be the unique point such that  $\frac{y-z}{|y-z|} = \tau$ .

Now let  $\omega$  be an affine function such that  $\omega(x_0) = u(x_0, t)$  and  $D\omega = Du(x_0, t)$ . Then  $\omega \leq u(x, t)$ ,  $x \in \Omega$  and

$$(3.5) \quad \begin{aligned} \omega(z) &= \omega(x_0) + D\omega(x_0) \cdot (z - x_0) \\ &= u(x_0, t) + Du(x_0, t) \cdot \frac{z - x_0}{|z - x_0|} \cdot |z - x_0| \\ &\geq u(x_0, t) - M_1 R, \end{aligned}$$

where we assume  $\varphi(x, u) \leq M_1$  in  $\bar{\Omega} \times [-C_0, C_0]$ . Therefore,

$$(3.6) \quad D_\tau u(x_0, t) = D_\tau \omega(x_0) = \frac{\omega(y) - \omega(z)}{|y - z|} \leq \frac{u(y, t) - u(x_0, t) + M_1 R}{R} \leq \frac{2C_0}{R} + M_1.$$

Since  $\tau$ ,  $x_0$ , and  $t$  are arbitrary, we are done.  $\square$

#### 4. $C^2$ ESTIMATES

First of all, we will list some evolution equations that will be used later. Since the calculations are straightforward, we will only state our results here.

**Lemma 4.1.** *Let  $u$  be a solution to the general curvature flow (1.11). Then we have the following evolution equations:*

$$\begin{aligned} (i) \quad & \frac{d}{dt}g_{ij} = -2(F - \Phi)h_{ij}, \\ (ii) \quad & \frac{d}{dt}\mathbf{n} = -g^{ij}(F - \Phi)_i\tau_j, \\ (iii) \quad & \frac{d}{dt}\mathbf{n}^{n+1} = -g^{ij}(F - \Phi)_i u_j, \\ (vi) \quad & \frac{d}{dt}h_i^j = (F - \Phi)_i^j + (F - \Phi)h_i^k h_k^j, \end{aligned}$$

where  $g_{ij}, h_{ij}$  are the first and second fundamental forms,  $\mathbf{n}$  is the upward unit normal to  $\Sigma(t)$ ,  $\mathbf{n}^{n+1} = \langle \mathbf{n}, e^{n+1} \rangle$ , and  $h_i^j = g^{jk}h_{ki}$ .

**4.1.  $C^2$  interior estimates.** In this subsection, we will prove the following theorem.

**Theorem 4.2.** *Let  $\Sigma(t) = \{(x, u(x, t)) | x \in \Omega, t \in [0, T]\}$  be the flow surfaces, where  $u(x, t)$  satisfies equation (1.11) and*

$$\mathbf{n}^{n+1} \geq 2a > 0 \text{ on } \Sigma(t), \forall t \in [0, T].$$

*For  $X \in \Sigma(t)$ , let  $\kappa_{\max}(X)$  be the largest principle curvature of  $\Sigma(t)$  at  $X$ . Then*

$$(4.1) \quad \max_{\Omega_T} \frac{\kappa_{\max}}{\mathbf{n}^{n+1} - a} \leq C_2(\Phi, |u|_{C^1}) \left( 1 + \max_{\partial\Omega_T} \kappa_{\max} \right),$$

where  $\Omega_T = \Omega \times (0, T]$ .

*Proof.* Let's consider

$$M_0 = \max_{\Omega_T} \frac{\kappa_{\max}}{\mathbf{n}^{n+1} - a},$$

we assume  $M_0 > 0$  is attained at an interior point  $(x_0, t_0) \in \Omega \times (0, T]$ . We can choose a coordinate such that  $\kappa_1 = \kappa_{\max}$ ,  $h_i^j = \kappa_i \delta_{ij}$ , and  $g_{ij} = \delta_{ij}$  at  $(x_0, t_0)$ . In the following,  $h_{ij}$ ,  $h_i^j$  means the same.

At  $(x_0, t_0)$ ,  $\psi = \frac{h_{11}}{\mathbf{n}^{n+1} - a}$  achieves its local maximum. Hence at this point we have

$$(4.2) \quad \frac{h_{11i}}{h_{11}} - \frac{\nabla_i \mathbf{n}^{n+1}}{\mathbf{n}^{n+1} - a} = 0.$$

Moreover, by Lemma 4.1

$$\begin{aligned} (4.3) \quad \frac{\partial}{\partial t} \psi &= \frac{\dot{h}_{11}}{\mathbf{n}^{n+1} - a} - \frac{h_{11} \dot{\mathbf{n}}^{n+1}}{(\mathbf{n}^{n+1} - a)^2} \\ &= \frac{1}{\mathbf{n}^{n+1} - a} \{ \nabla_{11} F - \nabla_{11} \Phi + (F - \Phi) \kappa_1^2 \} + \frac{h_{11}}{(\mathbf{n}^{n+1} - a)^2} (F - \Phi)_i u_i. \end{aligned}$$

Since

$$(4.4) \quad \nabla_{11} \Phi = \Phi_{x_1 x_1}(x, u) + 2\Phi_z u_1 + \Phi_z u_{11},$$

$$(4.5) \quad \nabla_{11}u = \langle X, e_{n+1} \rangle_{11} = \langle h_{11}\mathbf{n}, e_{n+1} \rangle = h_{11}\mathbf{n}^{n+1},$$

and

$$(4.6) \quad \begin{aligned} \nabla_{11}F &= F^{ij}h_{ij11} + F^{ij,rs}h_{ij1}h_{rs1} \\ &= F^{ij}(h_{11ij} - h_{11}^2h_{ij} + h_{ik}h_{kj}h_{11}) + F^{ij,rs}h_{ij1}h_{rs1}. \end{aligned}$$

Combine (4.3)-(4.6) we get at  $(x_0, t_0)$

$$(4.7) \quad \begin{aligned} &\frac{\partial}{\partial t}\psi - F^{ii}\nabla_{ii}\psi \\ &= \frac{1}{\mathbf{n}^{n+1} - a} \{ F^{ii}h_{ii11} + F^{ij,rs}h_{ij1}h_{rs1} - \nabla_{11}\Phi + (F - \Phi)\kappa_1^2 \} \\ &+ \frac{h_{11}}{(\mathbf{n}^{n+1} - a)^2} (F - \Phi)_i u_i - \frac{F^{ii}h_{11ii}}{\mathbf{n}^{n+1} - a} + \frac{h_{11}}{(\mathbf{n}^{n+1} - a)^2} F^{ii}\mathbf{n}_{ii}^{n+1} \\ &= \frac{1}{\mathbf{n}^{n+1} - a} F^{ii}(h_{ii}^2h_{11} - h_{11}^2h_{ii}) + \frac{F^{ij,rs}h_{ij1}h_{rs1}}{\mathbf{n}^{n+1} - a} \\ &- \frac{\nabla_{11}\Phi}{\mathbf{n}^{n+1} - a} + \frac{(F - \Phi)\kappa_1^2}{\mathbf{n}^{n+1} - a} + \frac{h_{11}}{(\mathbf{n}^{n+1} - a)^2} (F - \Phi)_i u_i \\ &+ \frac{h_{11}}{(\mathbf{n}^{n+1} - a)^2} F^{ii} (-\nabla_k h_{ii} u_k - h_{ii}^2 \mathbf{n}^{n+1}) \\ &\leq \frac{-ah_{11}}{(\mathbf{n}^{n+1} - a)^2} f_i \kappa_i^2 - \frac{\Phi \kappa_1^2}{\mathbf{n}^{n+1} - a} + \frac{F^{ij,rs}h_{ij1}h_{rs1}}{\mathbf{n}^{n+1} - a} \\ &+ \frac{C}{\mathbf{n}^{n+1} - a} - \frac{\Phi_z \kappa_1 \mathbf{n}^{n+1}}{\mathbf{n}^{n+1} - a} - \frac{\kappa_1}{(\mathbf{n}^{n+1} - a)^2} (\Phi_i + \Phi_z u_i) u_i, \end{aligned}$$

which yields,

$$(4.8) \quad 0 \leq \frac{-a\kappa_1}{(\mathbf{n}^{n+1} - a)^2} f_i \kappa_i^2 - \frac{\left( \inf_{\bar{\Omega} \times [-C_0, C_0]} \Phi \right) \kappa_1^2}{\mathbf{n}^{n+1} - a} + C\kappa_1,$$

thus

$$(4.9) \quad \kappa_1 \leq C = C(\Phi, |u|_{C^1}).$$

Therefore we conclude that

$$(4.10) \quad \max_{\Omega_T} \frac{\kappa_{\max}}{\mathbf{n}^{n+1} - a} \leq C_2 \left( 1 + \max_{\partial\Omega_T} \kappa_{\max} \right).$$

□



**4.2.  $C^2$  boundary estimates.** We use  $\nu$  for the outer unit normal of  $\partial\Omega$  and  $\tau$  for a direction that tangential to  $\partial\Omega$ . By the exactly same argument as Lemma 4.1 of [9] we have

**Lemma 4.3** (Mixed  $C^2$  estimates at the boundary). *Let  $u$  be the solution of our flow equation (1.11). Then the absolute value of  $u_{\tau\nu}$  remains a priori bounded on  $\partial\Omega$  during the evolution.*

Now we consider the function

$$(4.1) \quad V(x, \xi, t) := u_{\xi\xi} - 2(\xi \cdot \nu)\xi'_i(D_i\varphi - D_k u D_i \nu^k),$$

where  $\xi' = \xi - (\xi \cdot \nu)\nu$ . By Theorem 4.2, we may assume  $V(x, \xi, t)$  achieves its maximum at  $(x_0, t_0) \in \partial\Omega \times (0, T]$ , otherwise, we are done.

We will devide it into 3 cases.

(i).  **$\xi$  is tangential.** Computing the second tangential derivatives of the boundary condition we obtain

$$(4.2) \quad D_k u \delta_i \delta_j \nu^k + \delta_i \nu^k \delta_j D_k u + \delta_j \nu^k \delta_i D_k u + \nu^k \delta_i \delta_j D_k u = \delta_i \delta_j \varphi,$$

where  $\delta_i = (\delta_{ij} - \nu^i \nu^j)D_i$ . Therefore at  $(x_0, t_0)$  we have

$$(4.3) \quad \begin{aligned} D_{\xi\xi\nu} u &= \nu^k \xi_i \xi_j D_{ijk} u \\ &\leq -2(\delta_i \nu^k) D_{jk} u \xi_i \xi_j + (\delta_i \nu^j) \xi_i \xi_j D_{\nu\nu} u + \varphi_z D_{ij} u \xi_i \xi_j + C. \end{aligned}$$

Next since  $V$  attains its maximum at  $(x_0, t_0)$  we have

$$(4.4) \quad 0 \leq D_\nu V = u_{\xi\xi\nu} - a_k D_{k\nu} u - (D_\nu a_k) D_k u - D_\nu b,$$

where  $a_k = 2(\xi \cdot \nu)(\varphi_z \xi'_k - \xi'_i D_i \nu^k)$  and  $b = 2(\xi \cdot \nu)\xi'_k \varphi_{x_k}$ . Thus, using Lemma 4.3

$$(4.5) \quad u_{\xi\xi\nu} \geq a_\nu D_{\nu\nu} u - C = -C,$$

combine with (4.3) yields

$$(4.6) \quad -2(\delta_i \nu^k) D_{jk} u \xi_i \xi_j + (\delta_i \nu^j) \xi_i \xi_j u_{\nu\nu} - c_\varphi D_{ij} u \xi_i \xi_j + C \geq -C.$$

Therefore we have

$$(4.7) \quad D_{\xi\xi} u(x_0, t_0) \leq C(1 + D_{\nu\nu} u(x_0, t_0)).$$

(ii)  **$\xi$  is non-tangential.** We write  $\xi = \alpha\tau + \beta\nu$ , where  $\alpha = \xi \cdot \tau$ ,  $\beta = \xi \cdot \nu \neq 0$ . Then

$$(4.8) \quad \begin{aligned} D_{\xi\xi} u &= \alpha^2 D_{\tau\tau}^2 u + \beta^2 D_{\nu\nu}^2 u + 2\alpha\beta D_{\tau\nu} u \\ &= \alpha^2 D_{\tau\tau} u + \beta^2 D_{\nu\nu} u + V'(x, \xi), \end{aligned}$$

where  $V' = 2(\xi \cdot \nu)\xi'_i(D_i\varphi - D_k u D_i \nu^k)$ . Thus we get,

$$(4.9) \quad \begin{aligned} V(x_0, \xi, t_0) &= \alpha^2 V(x_0, \tau, t_0) + \beta^2 V(x_0, \nu, t_0) \\ &\leq \alpha^2 V(x_0, \xi, t_0) + \beta^2 V(x_0, \nu, t_0), \end{aligned}$$

which yeilds

$$(4.10) \quad u_{\xi\xi}(x_0, t_0) \leq C(1 + u_{\nu\nu}(x_0, t_0)).$$

(iii)**Double normal  $C^2$ -estimates at the boundary.** Let's recall our evolution equation

$$(4.11) \quad \begin{cases} \dot{u} = w \left[ F \left( \frac{\gamma^{ik} u_{kl} \gamma^{lj}}{w} \right) - \Phi(x, u) \right] \\ u_\nu = \varphi(x, u) \end{cases}$$

In the following we denote

$$G(D^2 u, Du) = F \left( \frac{\gamma^{ik} u_{kl} \gamma^{lj}}{w} \right),$$

then we have

$$(4.12) \quad G^{ij} := \frac{\partial G}{\partial u_{ij}} = \frac{1}{w} F^{kl} \gamma^{ik} \gamma^{lj},$$

$$(4.13) \quad G^s := \frac{\partial G}{\partial u_s} = -\frac{u_s}{w^2} F - \frac{2}{w(1+w)} F^{ij} a_{ik} (w u_k \gamma^{sj} + u_j \gamma^{ks}).$$

By the positivity of  $[a_{ij}]$ , it's easy to see that

$$(4.14) \quad \sum |G^i| \leq CF \leq \tilde{C}_0.$$

Now, let  $q(x) = -d(x) + Nd^2(x)$ , then  $q \in C^\infty$  in  $\Omega_\mu$  for some constant  $\mu \leq \tilde{\mu}$  small depending on  $\Omega$ , and  $N\mu \leq \frac{1}{8}$ . Since

$$-Dd(y_0) = \nu(x_0)$$

where  $x_0 \in \partial\Omega$  and  $\text{dist}(y_0, \partial\Omega) = \text{dist}(x_0, y_0)$ ,  $q$  satisfies the following properties in  $\Omega_\mu$  :

$$(4.15) \quad -\mu + N\mu^2 \leq q \leq 0; \quad \frac{1}{2} \leq |Dq| \leq 2.$$

It's also easy to see that  $\frac{Dq}{|Dq|} = \nu$  for unit outer normal  $\nu$  on the boundary.

Next, let

$$(4.16) \quad M = \max_{\partial\Omega \times [0, T]} u_{\nu\nu}$$

and  $Q(x, t) = Q(x) = (A + \frac{1}{2}M)q(x)$  in  $\Omega_\mu$ , where  $\mu, A, N$  are positive constant to be chosen later. We consider the following function

$$(4.17) \quad P(x, t) := Du \cdot Dq - \varphi - Q$$

**Lemma 4.4.** *For any  $(x, t) \in \bar{\Omega}_\mu \times [0, T]$ , if we choose  $A, N$  large,  $\mu$  small, then we have  $P(x, t) \geq 0$ .*

*Proof.* First, let's assume  $P(x, t)$  attains its minimum at  $(x_0, t_0) \in \Omega_\mu \times (0, T]$  and  $u_{ij}(x_0, t_0) = u_{ii}(x_0, t_0)\delta_{ij}$ . Differentiating  $P$  we get

$$(4.18) \quad P_i = \sum_l u_{li}q_l + \sum_l u_lq_{li} - \varphi_i - Q_i,$$

$$(4.19) \quad P_{ij} = \sum_l u_{lij}q_l + 2 \sum_l u_{li}q_{lj} + \sum_l u_lq_{lij} - \varphi_{ij} - Q_{ij},$$

and

$$(4.20) \quad \begin{aligned} P_t &= Du_t \cdot Dq - \varphi - Q \\ &= [w(F - \Phi)]_l q_l - \varphi_z u_t = [w(F - \Phi)]_l q_l - \varphi_z w(F - \Phi). \end{aligned}$$

Therefore at  $(x_0, t_0)$  we have

$$(4.21) \quad \begin{aligned} &\frac{1}{w}P_t - G^{ij}P_{ij} \\ &= \frac{1}{w}[w(F - \Phi)]_l q_l - \varphi_z(F - \Phi) - G^{ij}(\sum_l u_{lij}q_l + 2 \sum_l u_{li}q_{lj} \\ &\quad + \sum_l u_lq_{lij} - \varphi_{ij}) + (A + \frac{1}{2}M)G^{ij}q_{ij} \\ &= \frac{1}{w}[w(F - \Phi)]_l q_l - \varphi_z(F - \Phi) - G^{ii} \sum_l u_{lii}q_l \\ &\quad - 2G^{ii}u_{ii}q_{ii} - G^{ii}u_lq_{lii} + G^{ii}\varphi_{ii} + (A + \frac{1}{2}M)G^{ii}q_{ii}. \end{aligned}$$

This implies at  $(x_0, t_0)$

$$\begin{aligned}
 0 &\geq \frac{1}{w}P_t - G^{ii}P_{ii} \\
 &= \frac{(F - \Phi)}{w} \cdot \frac{u_l u_{ll} q_l}{w} + F_l q_l - \Phi_l q_l - \varphi_z(F - \Phi) \\
 (4.22) \quad &- G^{ii} \sum_l u_{lii} q_l - 2G^{ii} u_{ii} q_{ii} - \sum_l G^{ii} u_l q_{l ii} + G^{ii}(\varphi_{x_i x_i} + 2\varphi_{x_i z} u_i + \varphi_z u_{ii}) \\
 &+ (A + \frac{1}{2}M)G^{ii} q_{ii}.
 \end{aligned}$$

Since  $G(D^2 u, Du) = F$  we have

$$(4.23) \quad G^{ij} u_{ijl} + G^s u_{sl} = F_l,$$

which gives us

$$(4.24) \quad F_l q_l - G^{ij} u_{ijl} q_l = G^s u_{sl} q_l.$$

By (4.14) we have

$$(4.25) \quad |G^s u_{sl} q_l| = |G^l u_{ll} q_l| \leq \tilde{C}_1(M + 1).$$

Moreover, by the speed estimate (2.1) and the gradient estimate (3.3) it's easy to see

$$(4.26) \quad |\Phi_l q_l| + \left| \frac{F - \Phi}{w} \cdot \frac{u_l u_{ll} q_l}{w} + \varphi_z G^{ii} u_{ii} \right| \leq \tilde{C}_2 M.$$

Now, by the convexity of  $\partial\Omega$ , we can assume

$$(4.27) \quad 2k_0 \delta_{\alpha\beta} \leq -d_{\alpha\beta} \leq k_1 \delta_{\alpha\beta}, \quad 1 \leq \alpha, \beta \leq n - 1.$$

Thus in  $\Omega_\mu$  we have

$$(4.28) \quad (k_1 + 2N)\delta_{ij} \geq q_{ij} = -d_{ij} + 2N d d_{ij} + 2N d_i d_j \geq k_0 \delta_{ij},$$

where  $1 \leq i, j \leq n$ . We get

$$(4.29) \quad |2G^{ii} u_{ii} q_{ii}| \leq \tilde{C}_3(k_1 + 2N).$$

Since

$$(4.30) \quad q_{ijl} = -d_{ijl} + 2N d_l d_{ij} + 2N d d_{ijl} + 4N d_{il} d_j,$$

we get

$$(4.31) \quad |q_{ijl}| \leq C(|\partial\Omega|_{C^3}) + 6N k_1.$$

Therefore

$$(4.32) \quad |G^{ii}u_l q_{l ii}| \leq (C(|\partial\Omega|_{C^3}) + 6Nk_1) C_1 \sum G^{ii},$$

consequently we have

$$(4.33) \quad |G^{ii}u_l q_{l ii} + G^{ii}(\varphi_{x_i x_i} + 2\varphi_{x_i z} u_i)| \leq (\tilde{C}_4 + 6\tilde{C}_5 N k_1) \sum G^{ii}.$$

To conclude we obtained

$$(4.34) \quad \begin{aligned} 0 &\geq \frac{1}{w} P_t - G^{ii} P_{ii} \\ &\geq -\tilde{C}_2 M - \tilde{C}_1 (M + 1) - \tilde{C}_3 (k_1 + 2N) - (\tilde{C}_4 + 6\tilde{C}_5 N k_1) \sum G^{ii} \\ &\quad + (A/2 + 1/4M) k_0 \sum G^{ii} + (A/2 + 1/4M) G(D^2 q, Du), \end{aligned}$$

here we used the concavity of  $f$ , which gives us  $G^{ij}(D^2 u, Du) q_{ij} \geq G(D^2 q, Du)$ . By Lemma 2.2 of [4], we may choose  $N$  sufficiently large such that

$$(4.35) \quad \frac{1}{4} G(D^2 q, Du) \geq 2\tilde{C}_1 + \tilde{C}_2,$$

then we choose  $A$  such that

$$(4.36) \quad \frac{k_0}{2} A > \tilde{C}_3 (k_1 + 2N) + \tilde{C}_4 + 6N\tilde{C}_5 k_1.$$

Substitute (4.35) and (4.36) to (4.34) we get

$$(4.37) \quad \frac{1}{w} P_t - G^{ij} P_{ij} > 0$$

at  $(x_0, t_0)$ , leads to a contradiction.

Finally, since for any  $(x, t) \in \partial\Omega \cap \Omega_\mu \times [0, T]$  we have

$$P(x, t) = 0.$$

For  $(x, t) \in \partial\Omega_\mu \setminus \partial\Omega \times [0, T]$  we have

$$P(x, t) \geq -\tilde{C}_6 + (A + \frac{1}{2}M) \cdot \frac{1}{2}\mu > 0,$$

when  $A \geq \frac{2\tilde{C}_6}{\mu}$ . Moreover, when  $A \geq \tilde{C}_7 = \tilde{C}_7(|u_0|_{C^2}, |\varphi|_{C^1})$ , we have for  $x \in \Omega_\mu$

$$P(x, 0) \geq 0.$$

Thus, choose

$$A = \frac{2[\tilde{C}_3(k_1 + 2N) + \tilde{C}_4 + 6N\tilde{C}_5 k_1]}{k_0} + \frac{2\tilde{C}_6}{\mu} + \tilde{C}_7$$

we have  $P(x, t) \geq 0$  in  $\Omega_\mu \times [0, T]$ . □

**Theorem 4.5.** *Let  $\Omega$  be a smooth bounded, strictly convex domain in  $\mathbb{R}^n$ ,  $u$  is a smooth solution of (1.11),  $\nu$  is the outer unit normal vector of  $\partial\Omega$ . Then we have*

$$(4.38) \quad \max_{\partial\Omega \times [0, T]} u_{\nu\nu} \leq C.$$

*Proof.* Assume  $(z_0, t_0) \in \partial\Omega \times [0, T]$  is the maximum point of  $u_{\nu\nu}$  on  $\partial\Omega \times [0, T]$ . By Lemma 4.4 we have

$$(4.39) \quad \begin{aligned} 0 &\geq P_\nu(z_0, t_0) = \left( \sum_l u_{l\nu} q_l + u_l q_{l\nu} - \varphi_\nu \right) - \left( A + \frac{1}{2}M \right) q_\nu \\ &\geq u_{\nu\nu} - C(|u|_{C^1}, N, |\partial\Omega|_{C^2}, |\varphi|_{C^1}) - \left( A + \frac{1}{2}M \right), \end{aligned}$$

Therefore we have,

$$(4.40) \quad \max_{\partial\Omega \times [0, T]} u_{\nu\nu} \leq C + \frac{1}{2}M,$$

which implies (4.38). □

## 5. CONVERGENCE TO A STATIONARY SOLUTION

Let us go back to our original problem (1.11), which is a scalar parabolic differential equation defined on the cylinder  $\Omega_T = \Omega \times [0, T]$  with initial value  $u_0$ . In view of a priori estimates, which we have estimated in the preceding sections, we know that

$$(5.1) \quad |D^2 u| \leq C,$$

$$(5.2) \quad |Du| \leq C,$$

and

$$(5.3) \quad |u| \leq C.$$

Therefore,

$F$  is uniformly elliptic.

Moreover, since  $F$  is concave, we have uniform  $C^{2+\alpha}(\Omega)$  estimates for  $u(\cdot, t)$ ,  $\forall t \in [0, T]$ . We can repeat the process and conclude that the flow exists for all  $t \in [0, \infty)$ .

By integrating the flow equation with respect to  $t$  we get

$$(5.4) \quad u(x, t^*) - u(x, 0) = \int_0^{t^*} w(F - \Phi) dt.$$

In particular, by (5.3) we have

$$(5.5) \quad \int_0^\infty w(F - \Phi)dt < \infty \quad \forall x \in \Omega.$$

Hence for any  $x \in \Omega$  there exists a sequence  $t_k \rightarrow \infty$  such that  $F - \Phi \rightarrow 0$ . On the other hand,  $u(x, \cdot)$  is monotone increasing and bounded. Therefore,

$$(5.6) \quad \lim_{t \rightarrow \infty} u(x, t) = u^\infty(x)$$

exists, and is of class  $C^\infty(\bar{\Omega})$ . Moreover,  $u^\infty$  is a stationary solution of our problem, i.e.,  $f(\kappa[\Sigma^\infty]) = \Phi(x, u^\infty)$  and  $u_\nu^\infty = \phi(x, \infty)$ .

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